



# *Certificate of Publication*



This is to confirm that

**Yingxing Lan**

Published following article

**Multimodal Gait Control Algorithm for a Multifunctional  
Intelligent Hexapod Robot for Emergency Rescue**

Volume 13, Issue 10, pp: 10-13

[www.ijres.org](http://www.ijres.org)

**A Peer Reviewed referred Journal**

**Impact Factor : 7.52**

**International Journal of Research in Engineering and  
Science (IJRES)**

**ISSN: 2320-9364 IJRES is Peer Reviewed Refereed.**

**Editor-In-Chief**



# *Certificate of Publication*



This is to confirm that

**Lingfeng Zhang**

Published following article

**Multimodal Gait Control Algorithm for a Multifunctional  
Intelligent Hexapod Robot for Emergency Rescue**

Volume 13, Issue 10, pp: 10-13

**[www.ijres.org](http://www.ijres.org)**

**A Peer Reviewed referred Journal**

**Impact Factor : 7.52**

**International Journal of Research in Engineering and  
Science (IJRES)**

**ISSN: 2320-9364 IJRES is Peer Reviewed Refereed.**

**Editor-In-Chief**



# *Certificate of Publication*



This is to confirm that

**Jialin Chen**

Published following article

Multimodal Gait Control Algorithm for a Multifunctional  
Intelligent Hexapod Robot for Emergency Rescue

Volume 13, Issue 10, pp: 10-13

[www.ijres.org](http://www.ijres.org)

**A Peer Reviewed referred Journal**

**Impact Factor : 7.52**

**International Journal of Research in Engineering and  
Science (IJRES)**

**ISSN: 2320-9364** IJRES is Peer Reviewed Refereed.

**Editor-In-Chief**



# *Certificate of Publication*



This is to confirm that

**Yudong Qing**

Published following article

Multimodal Gait Control Algorithm for a Multifunctional  
Intelligent Hexapod Robot for Emergency Rescue

Volume 13, Issue 10, pp: 10-13

[www.ijres.org](http://www.ijres.org)

**A Peer Reviewed referred Journal**

**Impact Factor : 7.52**

**International Journal of Research in Engineering and  
Science (IJRES)**

**ISSN: 2320-9364** IJRES is Peer Reviewed Refereed.

**Editor-In-Chief**



# *Certificate of Publication*



This is to confirm that

**Lianhui Long**

Published following article

Multimodal Gait Control Algorithm for a Multifunctional  
Intelligent Hexapod Robot for Emergency Rescue

Volume 13, Issue 10, pp: 10-13

[www.ijres.org](http://www.ijres.org)

**A Peer Reviewed referred Journal**

**Impact Factor : 7.52**

**International Journal of Research in Engineering and  
Science (IJRES)**

**ISSN: 2320-9364** IJRES is Peer Reviewed Refereed.

**Editor-In-Chief**



# *Certificate of Publication*



This is to confirm that

**Yang Zhao**

Published following article

**Multimodal Gait Control Algorithm for a Multifunctional  
Intelligent Hexapod Robot for Emergency Rescue**

Volume 13, Issue 10, pp: 10-13

[www.ijres.org](http://www.ijres.org)

**A Peer Reviewed referred Journal**

**Impact Factor : 7.52**

**International Journal of Research in Engineering and  
Science (IJRES)**

**ISSN: 2320-9364 IJRES is Peer Reviewed Refereed.**

**Editor-In-Chief**